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Stabilization of Nonlinear Uncertain Systems Description: The efforts in nonlinear control over the last few years have led to the level of generality in which conceptual solutions to global Lyapunov stabilization and optimal control problems exist for all finite-dimensional continuous-time systems affine in control and the disturbance.

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Robust stabilization of a class of uncertain nonlinear

Abstract: This paper presents stability analysis for a class of uncertain nonlinear systems and a method for designing robust fuzzy controllers to stabilize the uncertain nonlinear systems, First, a stability condition for Takagi and Sugeno's fuzzy model is given in terms of Lyapunov stability theory.

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Stabilization of Nonlinear Uncertain Systems

This monograph presents the fundamentals of global stabilization and optimal control of nonlinear systems with uncertain models. It offers a unified view of deterministic disturbance attenuation,

stochastic control, and adaptive control for nonlinear systems. The book addresses researchers in the areas of robust and adaptive nonlinear control, nonlinear H-infinity stochastic control, and other related areas of control and dynamical systems theory.

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A new approach to global stabilization of high order time

Delightedly, combining constructive design with stability theorem perfectly, adding a power integrator method promoted the successful solutions to the stabilization problem and the tracking problem for high-order nonlinear systems, see , , , , , , , and the references therein.

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Stabilization of Nonlinear Uncertain Systems Miroslav Krstic and Hua Deng . Springer, 1998, ISBN 1-85233-020-1 . Preface and Contents . The efforts in nonlinear control over the last few years have led to the level of generality in which conceptual solutions to global Lyapunov stabilization and optimal control problems exist for all finite

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Stabilization of Nonlinear Uncertain Systems Miroslav

This monograph presents the fundamentals of global stabilization and optimal control of nonlinear systems with uncertain models. It offers a unified view of deterministic disturbance attenuation, stochastic control, and adaptive control for nonlinear systems.

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